```
Purpose: register and refine the pointings of a set of mutually overlapping
         input images using point source correlation. The method is only
         valid if the input images span no more than ~ one square deg. of sky.

Usage: relativrefine
    -n  <inp_namelist_fname>      (Optional)
    -f1 <inp_image_list_fname>    (Required)
    -f2 <inp_table_list_fname>    (Required)
    -f3 <inp_fiducial_frame_table>(Optional, Default = Input frame
                                   with maximum no. of overlaps)
    -o  <out_table_fname>         (Optional, Input headers always updated)
    -sr <Max_Search_Radius>       (Optional [arcsec], Default = 1.5)
    -sf <Max_Flux_Diff>           (Optional [percent], Default = 5)
    -st <Flux_Threshold>          (Optional [source extractor units],
                                   Default = 0)
    -l  <log_fname>               (Optional, Default = `stdout')
    -a  <ancillary_file_path>     (Optional)
    -d  (prints debug statements)
    -v  (verbose output)
    -vv (superverbose output)
```